

OPTIMAL CONTROL OF NONLINEAR PROCESSES%0A

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Optimal Control of Nonlinear Processes - UNTAG Part II begins with material specifically on nonlinear optimal control. Chapter 3 is in some sense the heart of the book, introducing, explaining, and applying Pontryagin's Maximum Principle.

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Optimal Control of Nonlinear Switched Systems ...

Optimal Control of Nonlinear Switched Systems 277 where the coefficients in the linear combination are decision variables to be chosen optimally.

Self-Learning Optimal Control of Nonlinear Systems ...

The optimal number of control steps can also be obtained by the present (ϵ) -optimal control algorithm for the unfixed initial state. Neural networks are used to approximate the performance index function, and compute the optimal control law, respectively, for facilitating the implementation of the (ϵ) -optimal control algorithm.

NONLINEAR OPTIMAL CONTROL: A CONTROL LYAPUNOV FUNCTION AND ...

approach to the solution of the optimal control problem. The HJB partial differential equation solves the optimal control problem for every initial condition all at once. In this sense it is a global approach, and provides a closed-loop (state-feedback) formula for the optimal control action (eqn. 5).

Nonlinear Optimization for Optimal Control - People
Nonlinear Optimization for Optimal Control Pieter Abbeel
UC Berkeley EECS Many slides and figures adapted from
Stephen Boyd [optional] Boyd and Vandenberghe, Convex
Optimization, Chapters 9-11

Control Applications of Nonlinear Programming and ...
Control Applications of Nonlinear Programming and
Optimization presents the proceedings of the Fifth IFAC
Workshop held in Capri, Italy on June 11-14, 1985. The
book covers various aspects of the optimization of control
systems and of the numerical solution of optimization
problems.

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Processes (eBook + PDF) Dynamic optimization is rocket
science and more. This volume teaches researchers and
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optimization to solve practical problems.

An Anticipatory Terminal Iterative Learning Control
...

This work presents an anticipatory terminal iterative
learning control scheme for a class of batch processes,
where only the final system output is measurable and the
control input is constant in each operations. The proposed
approach works well with input constraints provided that
the desired control input with respect to the desired
trajectory is within the saturation bound. The tracking

Linear Quadratic Optimal Control - University of
Minnesota

2. The optimal control law is in the form of a time varying
linear state feedback $u(t) = K(t)x(t)$ with feedback gain
 $K(t) := R^{-1}(t)B^T(t)P(t)$. The open loop optimal control can
be obtained, if so desired, by integrating (6.1) with the
control (6.12). It is, however, much better to utilize
feedback than to use openloop. 3.

Optimal control - Wikipedia

Optimal control problems are generally nonlinear and
therefore, generally do not have analytic solutions (e.g.,
like the linear-quadratic optimal control problem). As a
result, it is necessary to employ numerical methods to
solve optimal control problems.